NAG C Library Function Document

nag_dtptrs (f07uec)

1 Purpose

nag_dtptrs (f07uec) solves a real triangular system of linear equations with multiple right-hand sides, $AX = B$ or $A^TX = B$, using packed storage.

2 Specification

```
void nag_dtptrs (Nag_OrderType order, Nag_UploType uplo, Nag_TransType trans,
     Nag_DiagType diag, Integer n, Integer nrhs, const double ap[], double b[],
     Integer pdb, NagError *fail)
```

3 Description

nag_dtptrs (f07uec) solves a real triangular system of linear equations $AX = B$ or $A^TX = B$ using packed storage.

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

Higham N J (1989) The accuracy of solutions to triangular systems *SIAM J. Numer. Anal.* **26** 1252–1265

5 Parameters

1: **order** – Nag_OrderType *Input*

On entry: the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = **Nag_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.

Constraint: **order** = **Nag_RowMajor** or **Nag_ColMajor**.

2: **uplo** – Nag_UploType *Input*

On entry: indicates whether A is upper or lower triangular as follows:

if **uplo** = **Nag_Upper**, A is upper triangular;

if **uplo** = **Nag_Lower**, A is lower triangular.

Constraint: **uplo** = **Nag_Upper** or **Nag_Lower**.

3: **trans** – Nag_TransType *Input*

On entry: indicates the form of the equations as follows:

if **trans** = **Nag_NoTrans**, the equations are of the form $AX = B$;

if **trans** = **Nag_Trans** or **Nag_ConjTrans**, the equations are of the form $A^TX = B$.

Constraint: **trans** = **Nag_NoTrans**, **Nag_Trans** or **Nag_ConjTrans**.

4: **diag** – Nag_DiagType *Input*

On entry: indicates whether A is a non-unit or unit triangular matrix as follows:

if **diag** = **Nag_NonUnitDiag**, A is a non-unit triangular matrix;

if **diag** = **Nag_UnitDiag**, A is a unit triangular matrix; the diagonal elements are not referenced and are assumed to be 1.

Constraint: **diag** = **Nag_NonUnitDiag** or **Nag_UnitDiag**.

5: **n** – Integer *Input*

On entry: n, the order of the matrix A.

Constraint: **n** ≥ 0.

6: **nrhs** – Integer *Input*

On entry: r, the number of right-hand sides.

Constraint: **nrhs** ≥ 0.

7: **ap**[dim] – const double *Input*

Note: the dimension, dim, of the array **ap** must be at least $\max(1, \mathbf{n} \times (\mathbf{n}+1)/2)$.

On entry: the n by n triangular matrix A, packed by rows or columns. The storage of elements a_{ij} depends on the **order** and **uplo** parameters as follows:

if **order** = **Nag_ColMajor** and **uplo** = **Nag_Upper**,
a_{ij} is stored in **ap**$[(j-1) \times j/2 + i - 1]$, for $i \leq j$;

if **order** = **Nag_ColMajor** and **uplo** = **Nag_Lower**,
a_{ij} is stored in **ap**$[(2n-j) \times (j-1)/2 + i - 1]$, for $i \geq j$;

if **order** = **Nag_RowMajor** and **uplo** = **Nag_Upper**,
a_{ij} is stored in **ap**$[(2n-i) \times (i-1)/2 + j - 1]$, for $i \leq j$;

if **order** = **Nag_RowMajor** and **uplo** = **Nag_Lower**,
a_{ij} is stored in **ap**$[(i-1) \times i/2 + j - 1]$, for $i \geq j$.

8: **b**[dim] – double *Input/Output*

Note: the dimension, dim, of the array **b** must be at least $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$ when **order** = **Nag_ColMajor** and at least $\max(1, \mathbf{pdb} \times \mathbf{n})$ when **order** = **Nag_RowMajor**.

If **order** = **Nag_ColMajor**, the (i,j)th element of the matrix B is stored in **b**$[(j-1) \times$ **pdb** $+ i - 1]$ and if **order** = **Nag_RowMajor**, the (i,j)th element of the matrix B is stored in **b**$[(i-1) \times$ **pdb** $+ j - 1]$.

On entry: the n by r right-hand side matrix B.

On exit: the n by r solution matrix X.

9: **pdb** – Integer *Input*

On entry: the stride separating matrix row or column elements (depending on the value of **order**) in the array **b**.

Constraints:

if **order** = **Nag_ColMajor**, **pdb** $\geq \max(1, \mathbf{n})$;
if **order** = **Nag_RowMajor**, **pdb** $\geq \max(1, \mathbf{nrhs})$.

10: **fail** – NagError * *Output*

The NAG error parameter (see the Essential Introduction).

6 Error Indicators and Warnings

NE_INT

On entry, **n** = ⟨*value*⟩.
Constraint: **n** ≥ 0.

On entry, **nrhs** = ⟨*value*⟩.
Constraint: **nrhs** ≥ 0.

On entry, **pdb** = ⟨*value*⟩.
Constraint: **pdb** > 0.

NE_INT_2

On entry, **pdb** = ⟨*value*⟩, **n** = ⟨*value*⟩.
Constraint: **pdb** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = ⟨*value*⟩, **nrhs** = ⟨*value*⟩.
Constraint: **pdb** $\geq \max(1, \mathbf{nrhs})$.

NE_SINGULAR

The matrix A is singular.

NE_ALLOC_FAIL

Memory allocation failed.

NE_BAD_PARAM

On entry, parameter ⟨*value*⟩ had an illegal value.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy

The solutions of triangular systems of equations are usually computed to high accuracy. See Higham (1989).

For each right-hand side vector b, the computed solution x is the exact solution of a perturbed system of equations $(A + E)x = b$, where

$$|E| \leq c(n)\epsilon|A|,$$

$c(n)$ is a modest linear function of n, and ϵ is the ***machine precision***.

If $\hat{x}$ is the true solution, then the computed solution x satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_\infty}{\|x\|_\infty} \leq c(n)\,\mathrm{cond}(A, x)\epsilon, \quad \text{provided} \quad c(n)\,\mathrm{cond}(A, x)\epsilon < 1,$$

where $\mathrm{cond}(A, x) = \||A^{-1}|\,|A|\,|x|\|_\infty / \|x\|_\infty$.

Note that $\mathrm{cond}(A, x) \leq \mathrm{cond}(A) = \||A^{-1}|\,|A|\|_\infty \leq \kappa_\infty(A)$; $\mathrm{cond}(A, x)$ can be much smaller than $\mathrm{cond}(A)$ and it is also possible for $\mathrm{cond}(A^T)$ to be much larger (or smaller) than $\mathrm{cond}(A)$.

Forward and backward error bounds can be computed by calling nag_dtprfs (f07uhc), and an estimate for $\kappa_\infty(A)$ can be obtained by calling nag_dtpcon (f07ugc) with **norm** = **Nag_InfNorm**.

8 Further Comments

The total number of floating-point operations is approximately n^2r.

The complex analogue of this function is nag_ztptrs (f07usc).

9 Example

To solve the system of equations $AX = B$, where

$$A = \begin{pmatrix} 4.30 & 0.00 & 0.00 & 0.00 \\ -3.96 & -4.87 & 0.00 & 0.00 \\ 0.40 & 0.31 & -8.02 & 0.00 \\ -0.27 & 0.07 & -5.95 & 0.12 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} -12.90 & -21.50 \\ 16.75 & 14.93 \\ -17.55 & 6.33 \\ -11.04 & 8.09 \end{pmatrix},$$

using packed storage for A.

9.1 Program Text

```
/* nag_dtptrs (f07uec) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>
#include <nagx04.h>

int main(void)
{
  /* Scalars */
  Integer ap_len, i, j, n, nrhs, pdb;
  Integer exit_status=0;
  Nag_UploType uplo_enum;

  NagError fail;
  Nag_OrderType order;
  /* Arrays */
  char    uplo[2];
  double  *ap=0, *b=0;

#ifdef NAG_COLUMN_MAJOR
#define A_UPPER(I,J) ap[J*(J-1)/2 + I - 1]
#define A_LOWER(I,J) ap[(2*n-J)*(J-1)/2 + I - 1]
#define B(I,J) b[(J-1)*pdb + I - 1]
  order = Nag_ColMajor;
#else
#define A_LOWER(I,J) ap[I*(I-1)/2 + J - 1]
#define A_UPPER(I,J) ap[(2*n-I)*(I-1)/2 + J - 1]
#define B(I,J) b[(I-1)*pdb + J - 1]
  order = Nag_RowMajor;
#endif

  INIT_FAIL(fail);
  Vprintf("f07uec Example Program Results\n\n");

  /* Skip heading in data file */
  Vscanf("%*[^\n] ");
  Vscanf("%ld%ld%*[^\n] ", &n, &nrhs);
  ap_len = n*(n+1)/2;
#ifdef NAG_COLUMN_MAJOR
  pdb = n;
#else
  pdb = nrhs;
#endif
```

```
  /* Allocate memory */
  if ( !(ap = NAG_ALLOC(ap_len, double)) ||
       !(b = NAG_ALLOC(n * nrhs, double)) )
    {
      Vprintf("Allocation failure\n");
      exit_status = -1;
      goto END;
    }

  /* Read A and B from data file */
  Vscanf(" ' %1s '%*[^\n] ", uplo);
  if (*(unsigned char *)uplo == 'L')
    uplo_enum = Nag_Lower;
  else if (*(unsigned char *)uplo == 'U')
    uplo_enum = Nag_Upper;
  else
    {
      Vprintf("Unrecognised character for Nag_UploType type\n");
      exit_status = -1;
      goto END;
    }
  if (uplo_enum == Nag_Upper)
    {
      for (i = 1; i <= n; ++i)
        {
          for (j = i; j <= n; ++j)
            Vscanf("%lf", &A_UPPER(i,j));
        }
      Vscanf("%*[^\n] ");
    }
  else
    {
      for (i = 1; i <= n; ++i)
        {
          for (j = 1; j <= i; ++j)
            Vscanf("%lf", &A_LOWER(i,j));
        }
      Vscanf("%*[^\n] ");
    }
  for (i = 1; i <= n; ++i)
    {
      for (j = 1; j <= nrhs; ++j)
        Vscanf("%lf", &B(i,j));
    }
  Vscanf("%*[^\n] ");

  /* Compute solution */
  f07uec(order, uplo_enum, Nag_NoTrans, Nag_NonUnitDiag, n,
         nrhs, ap, b, pdb, &fail);
  if (fail.code != NE_NOERROR)
    {
      Vprintf("Error from f07uec.\n%s\n", fail.message);
      exit_status = 1;
      goto END;
    }
  /* Print solution */
  x04cac(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, nrhs,
         b, pdb, "Solution(s)", 0, &fail);
  if (fail.code != NE_NOERROR)
    {
      Vprintf("Error from x04cac.\n%s\n", fail.message);
      exit_status = 1;
      goto END;
    }
 END:
  if (ap) NAG_FREE(ap);
  if (b) NAG_FREE(b);

return exit_status;
}
```

9.2 Program Data

```
f07uec Example Program Data
  4  2                          :Values of N and NRHS
  'L'                           :Value of UPLO
  4.30
 -3.96  -4.87
  0.40   0.31  -8.02
 -0.27   0.07  -5.95   0.12    :End of matrix A
-12.90 -21.50
 16.75  14.93
-17.55   6.33
-11.04   8.09                  :End of matrix B
```

9.3 Program Results

```
f07uec Example Program Results

 Solution(s)
              1           2
 1     -3.0000     -5.0000
 2     -1.0000      1.0000
 3      2.0000     -1.0000
 4      1.0000      6.0000
```